

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	1	("20060173578").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 09:50
S2	1452	slippage and robot	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/22 14:07
S3	841	slippage and robot and @py<="2004"	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/22 14:08
S4	4	slippage same means and robot and @py<="2004"	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/22 14:08
S5	62	slip\$4 near5 determin\$3 and robot and @py<="2004"	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/22 14:10
S6	4	slip\$4 near5 determin\$3 and mobile robot and @py<="2004"	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/22 14:12
S7	2148	(700/245).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:14
S8	357	(700/247).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:35
S9	308	(700/251).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:35
S10	318	(700/253).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:35
S11	202	(700/257).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:35
S12	526	(700/258).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:35
S13	364	(700/260).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:36
S14	225	(700/261).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:36
S15	900	(318/568.1).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:36
S16	685	(318/568.11).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:36
S17	755	(318/568.12).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:36
S18	263	(318/568.13).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:36
S19	96	(318/568.14).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:36
S20	133	(318/568.15).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:36

S21	377	(318/568.16).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:36
S22	141	(318/568.17).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:36
S23	187	(318/568.18).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:36
S24	111	(318/568.19).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:37
S25	227	(318/568.2).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:37
S26	193	(318/568.21).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:37
S27	239	(318/568.22).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:37
S28	61	(318/568.23).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:37
S29	85	(318/568.24).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:37
S30	58	(318/568.25).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:37
S31	42107	("700").CLAS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:37
S32	9430	("706").CLAS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:37
S33	6428	("901").CLAS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/12/22 14:37
S34	2907	(S7 or S8 or S9 or S10 or S11 or S12 or S13 or S14 or S15 or S16 or S17 or S18 or S19 or S20 or S21 or S22 or S23 or S24 or S25 or S26 or S27 or S28 or S29 or S30) and @py<="2004"	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/22 14:39
S35	36147	(S31 or S32 or S33) and @py<="2004"	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/22 14:40
S36	98	slippage and S34	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/22 14:40
S37	435	slippage and S35	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/22 14:40
S38	0	slippage detect and S35	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/22 14:40
S39	40	slippage and (gait or walk \$3 or run\$4) and leg and S34	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/22 14:43
S40	575	(slip or slippage) same (frequency or spring) and robot	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/23 08:35

S41	377	S40 and @py<= "2004"	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/23 08:35
S42	19	(slip or slippage) same (frequency and spring) and robot	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/23 08:35
S43	9	((slip or slippage) same (frequency and spring) and robot and @py<= "2004"	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/23 08:36
S44	35	("3270554" "3509583" "3662234" "3948093" "3952880" "4132318" "4414984" "4471369" "4478089" "4483203" "4488441" "4521685" "4526043" "4555953" "4577513" "4588348"). PN. OR ("4695963"). URPN.	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/23 08:39
S45	173	leg near3 robot and slip	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/23 08:47
S46	58	S45 and @py<= "2004"	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/23 08:47
S47	73	leg near3 robot and (slip same (calculat\$3 or determin\$5))	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/23 08:48
S48	13	leg near3 robot and (slip with (calculat\$3 or determin\$5))	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/23 08:49
S49	10	leg near3 robot and (slip and spring constant)	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/23 08:54
S50	458	robot and band-pass	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/23 10:59
S51	59	robot and band-pass and slip	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/23 10:59
S52	30	robot and band-pass and slip and @py<= "2004"	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/23 11:00
S53	4	robot and band-pass and slip near5 (surface or floor) and @py<= "2004"	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/23 11:06
S54	47	("5402050" "5404086" "5432417" "5757834" "5808433" "5872893"). PN. OR ("6289265"). URPN.	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/23 11:34
S55	16	("4703240" "4811229" "5378969" "5402050" "5416393" "5421426" "5838130") PN. OR ("6021363") URPN.	US-PGPUB; USPAT; USOCR	ADJ	ON	2008/12/23 11:34

S56	18	("4834200" "5206569" "5209126" "5221883" "5255753" "5483630").PN. OR ("5644204").URPN.	US_PGPUB; USPAT; USOCR	ADJ	ON	2008/12/23 14:31
S57	0	("2003/0009259").URPN.	USPAT	ADJ	ON	2008/12/23 14:32
S58	191	(slip with (narrow or reduce)) and robot	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:12
S59	48	(range with (set or setting) with means) and robot	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:13
S60	282	((slip or slippage) with determin\$5) and robot	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:13
S61	276	gait with motion and robot	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:14
S62	0	S58 and S59 and S60 and S61	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:14
S63	8149	(range with (set or setting)) and robot	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:15
S64	4	S58 and S60 and S61 and S63	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:15

S65	23	S60 and S61	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:21
S66	0	(permissible range setting means).clm.	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:23
S67	0	(slippage determining means)".clm"	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:23
S68	0	desired "gait.clm"	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:24
S69	0	"permissible range setting means"".clm"	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:24
S70	0	(a control device)".clm"	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:25
S71	0	(permissible with range with setting)".clm"	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:27
S72	0	(slip with robot with gait)".clm"	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:28

S73	0	(slip with gait)".clm"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:28
S74	0	"slippage.clm"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:28
S75	0	(permissible with range with setting)".clm."	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:29
S76	0	(slip with robot with gait)".clm."	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:29
S77	0	(slip with gait)".clm."	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:29
S78	0	"slippage.clm."	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:29
S79	88	(robot with gait).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:30
S80	1353	(range setting).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:34

S81	14	((permissible range setting)).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:35
S82	2490	(instantaneous value).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:36
S83	15	(instantaneous value with robot).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:37
S84	4	(slippage with spring constant).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:38
S85	57	(slippage with frequency).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:39
S86	7	(slippage with frequency with filter).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/10 11:39
S87	44803	((narrow or narrow or tight or small or less) with range).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/15 07:42
S88	48	(((narrow or narrow or tight or small or less) with range) and robot).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	ADJ	ON	2009/06/15 07:42

6/ 15/ 2009 8:07:30 AM

C:\Documents and Settings\jsample\My Documents\EAST\Workspaces\10-562327.wsp